AMENDMENT TO THE CLAIMS

The following is a complete, marked up listing of revised claims with a status identifier in parentheses, underlined text indicating insertions, and strikethrough and/or double brackets indicating deletions.

LISTING OF CLAIMS

1. (Currently Amended) A method of estimating a signal-to-interference+noise ratio (SINR), comprising:

estimating polarities of a plurality of received data symbol samples;

converting the received plurality of data symbol samples into plurality of quasi-pilot symbol samples based on the estimated polarities by multiplying each of the plurality of received data symbol sample by an associated estimated polarity; and

generating an SINR estimate based on the plurality of quasi-pilot symbol samples <u>using</u> the multiplication results as the plurality of quasi-pilot symbol samples in an SINR estimation <u>algorithm</u> such that the SINR estimate is not dependent only on the polarities of the plurality of received data symbol samples.

- 2. (Cancelled)
- 3. (Currently Amended) A method of estimating a signal-to-interference+noise ratio (SINR), comprising:

estimating bit values of a plurality of received data symbol samples;

converting the received plurality of data symbol samples into plurality of quasi-pilot

symbol samples based on the estimated polarities by multiplying each of the plurality of received

data symbol sample by an associated estimated polarity; and

generating an SINR estimate based on the plurality of quasi-pilot symbol samples using

the multiplication results as the plurality of quasi-pilot symbol samples in an SINR estimation

algorithm such that the SINR estimate is not dependent only on a bit value of the plurality of

received data symbol samples.

4. (Cancelled)

5. (Currently Amended) A method of estimating a signal-to-interference+noise ratio

(SINR), comprising:

estimating polarities of a plurality of received data symbol samples;

converting the received data symbol samples into quasi-pilot symbol samples based on

the estimated polarities by multiplying each of the plurality of received data symbol sample by

an associated estimated polarity; and

generating an SINR estimate based on the quasi-pilot symbol samples using the

multiplication results as the plurality of quasi-pilot symbol samples in an SINR estimation

algorithm.

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